



Automated test of the AMG Speedshift DCT control software

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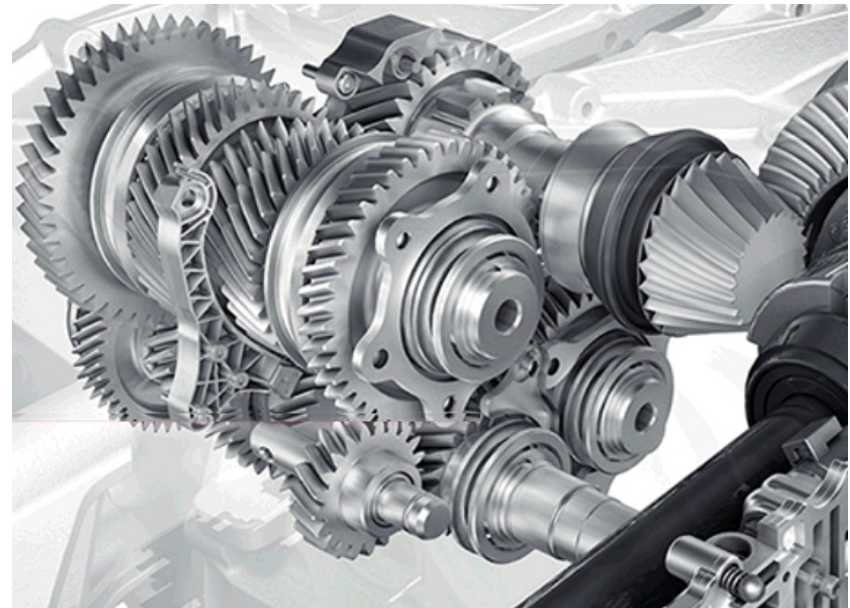
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- Motivation
- Principle of the scenario generator
- Test of AMG Speedshift DCT control software
 - the AMG Speedshift DCT
 - the software test setup
- Results and conclusion



Ever growing complexity
of automotive controllers

How to validate and test?

- do more road tests ?
- write more test scripts ?

This does not scale well
Code size grows faster
New processes needed

Idea

- increase degree of automation
- generate and evaluate useful test scenarios automatically

- After initial coding you can expect one bug per 20 lines of code
- After thorough unit testing you can expect 1 bug per 1000 lines of code in the final release
 - 1 line ~5 bytes, so 1 bug per ~5KB

| Application | Code Size | Statistics |
|----------------------------|-----------|------------|
| Steering Angle Sensor | 32KB | 7 Bugs |
| Low-end Sensor Cluster | 128KB | 26 Bugs |
| Airbag Controller | 256KB | 52 Bugs |
| EPS Controller | 512KB | 104 Bugs |
| Central Chassis Controller | 1.5MB | 308 Bugs |

source: presentation by Hans Adlkofer, Infineon, 2009

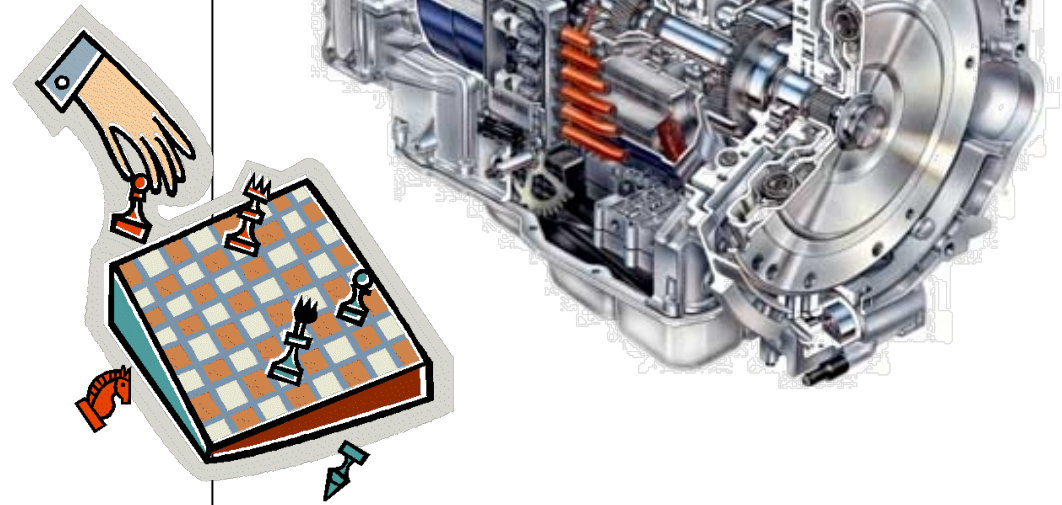
Idea

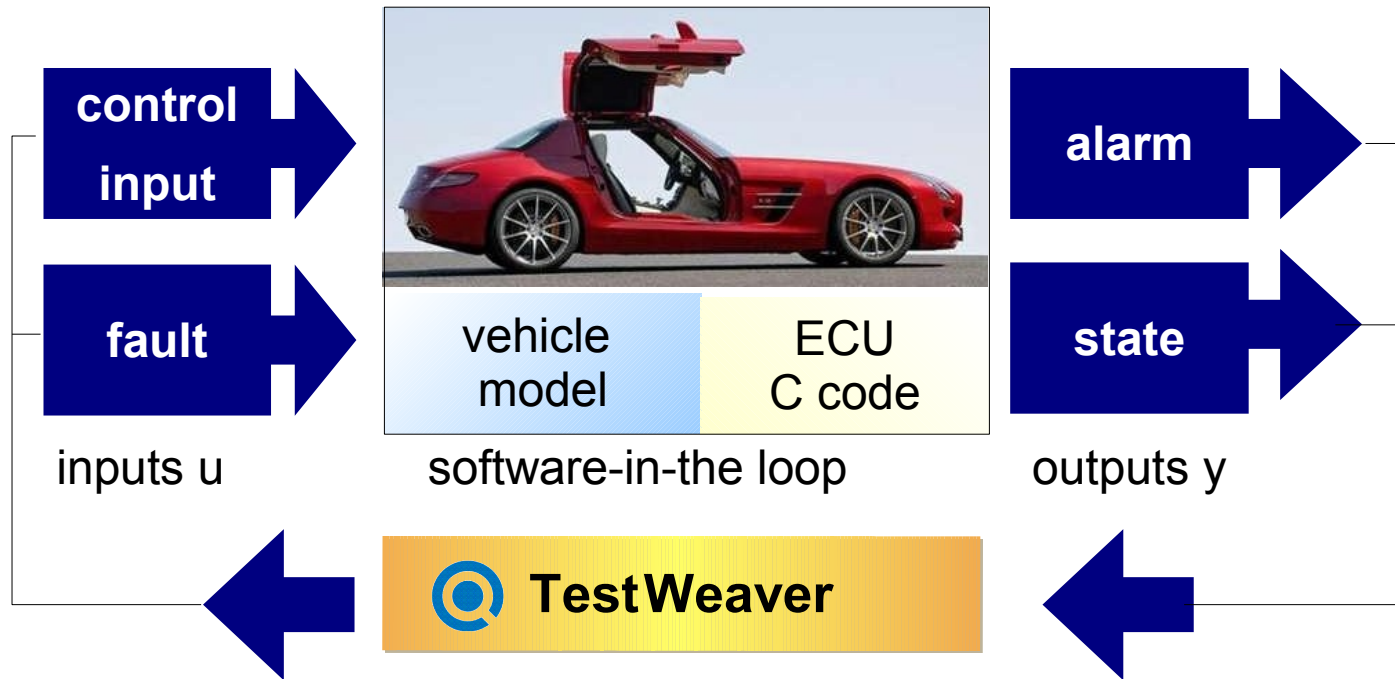
- intelligent generation of 1000s of differing test scenarios
- active attempt to:
 - maximize state coverage
 - drive the system in “difficult” situations

Benefit

- high coverage
- low efforts for test specification

**Testing =
playing against (simulated) system**

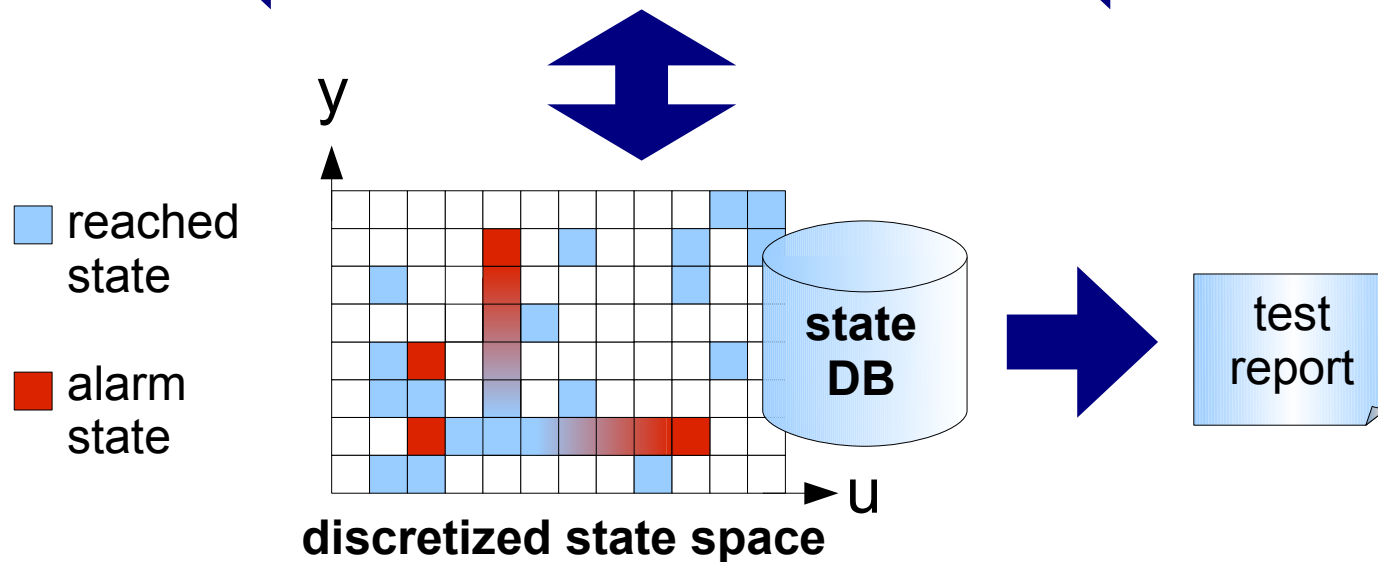


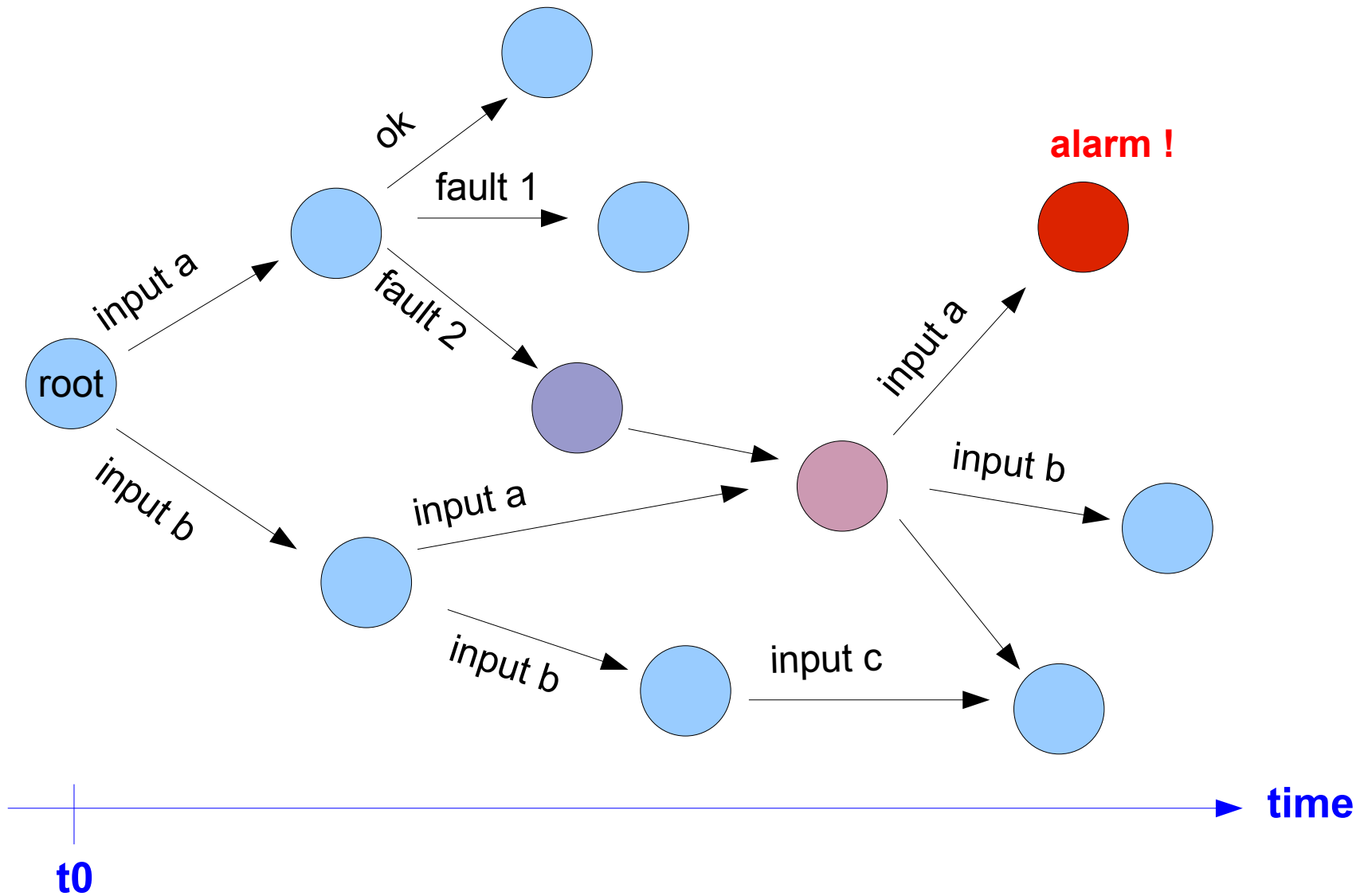


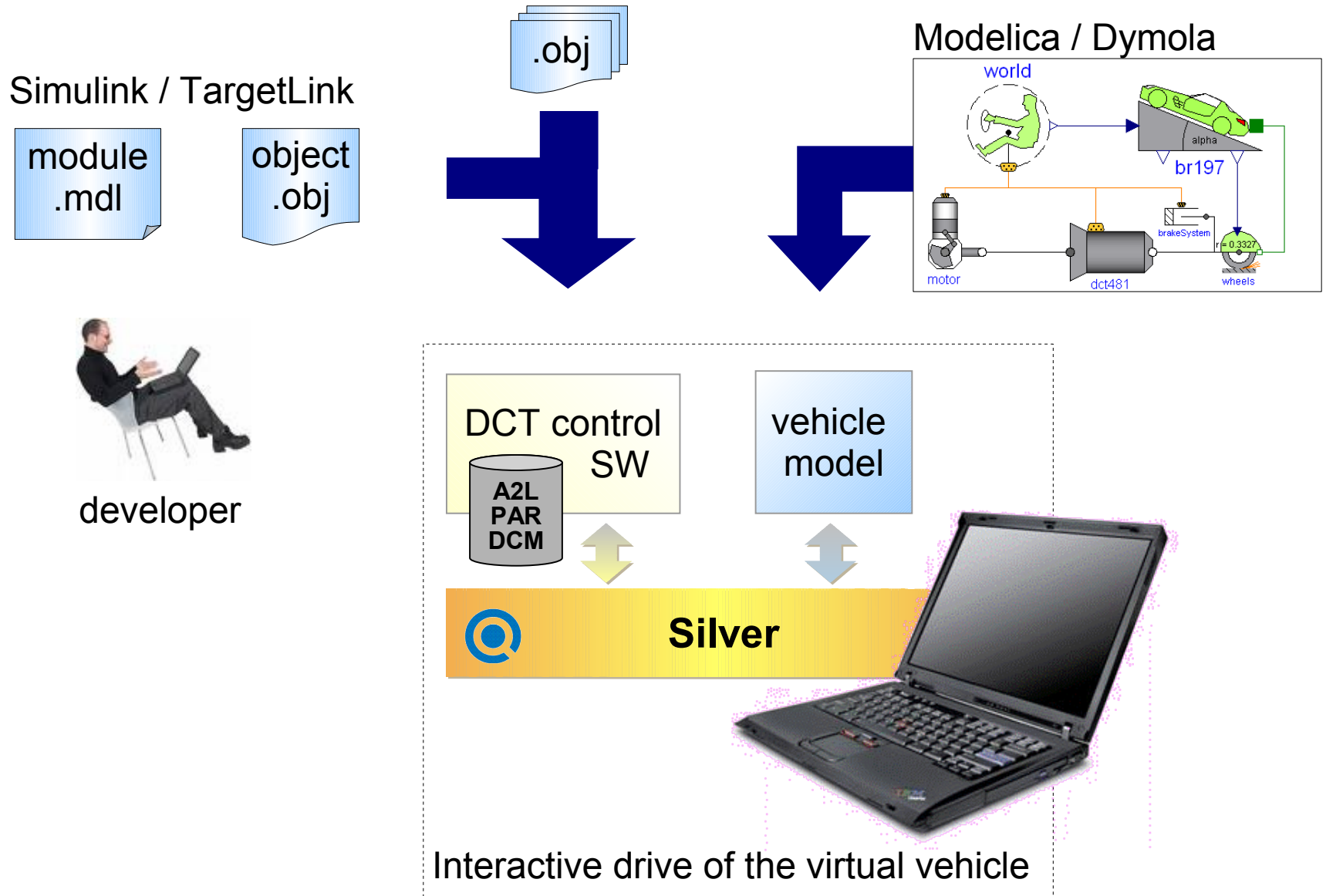
GOALS

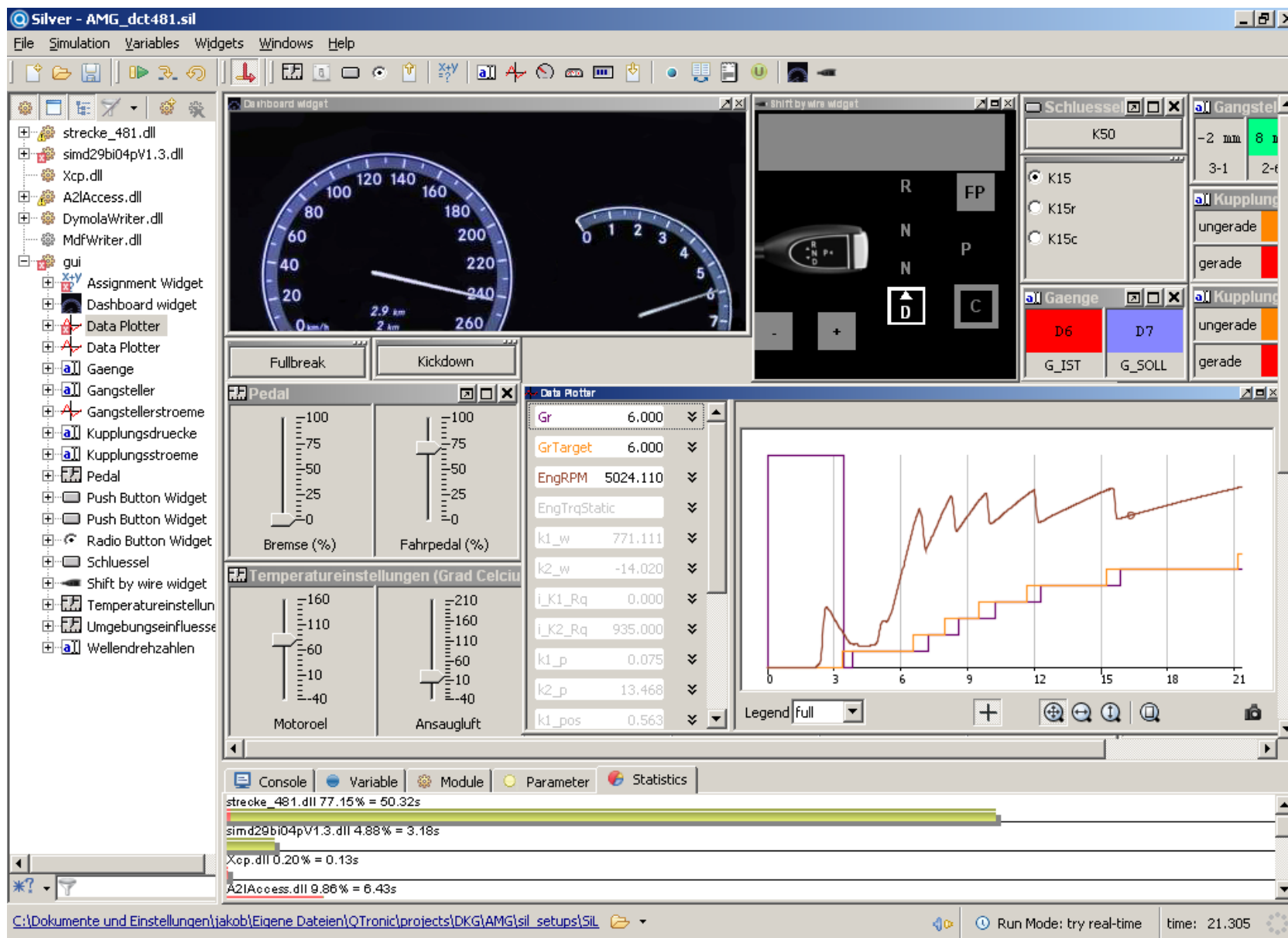
find bugs:
Change sub-optimal scenarios to generate worst-cases

coverage:
Drive the system in states that have not been reached before





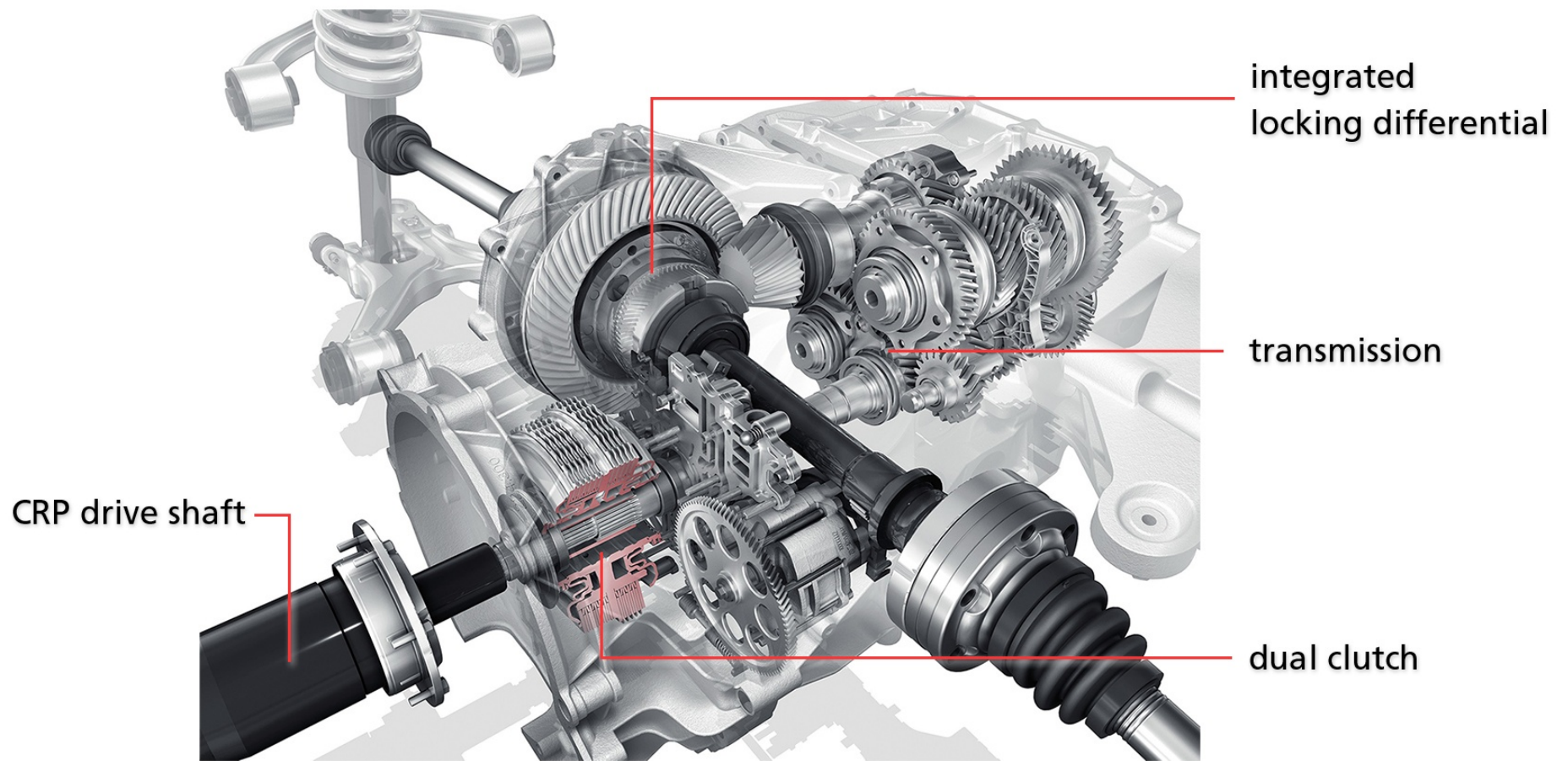




DCT with mechanical locking differential



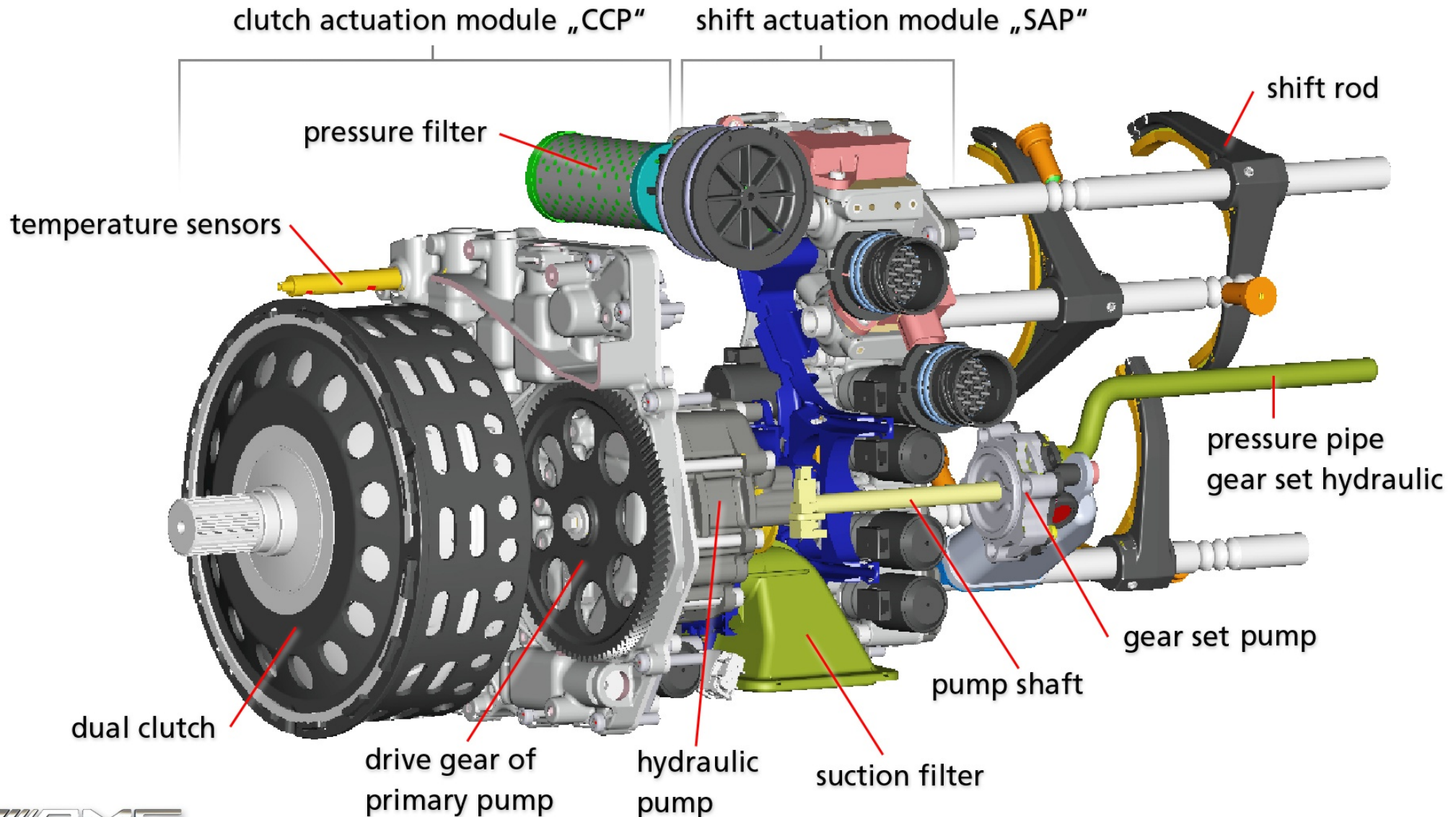
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Hydraulic unit of the DCT



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Source: Hart et.al., The function development and application of the DCT in the Mercedes-Benz SLS AMG.
VDI-Berichte 2081: Getriebe in Fahrzeugen 2010, pp. 599-615

Drivetrain of the Mercedes-Benz SLS AMG

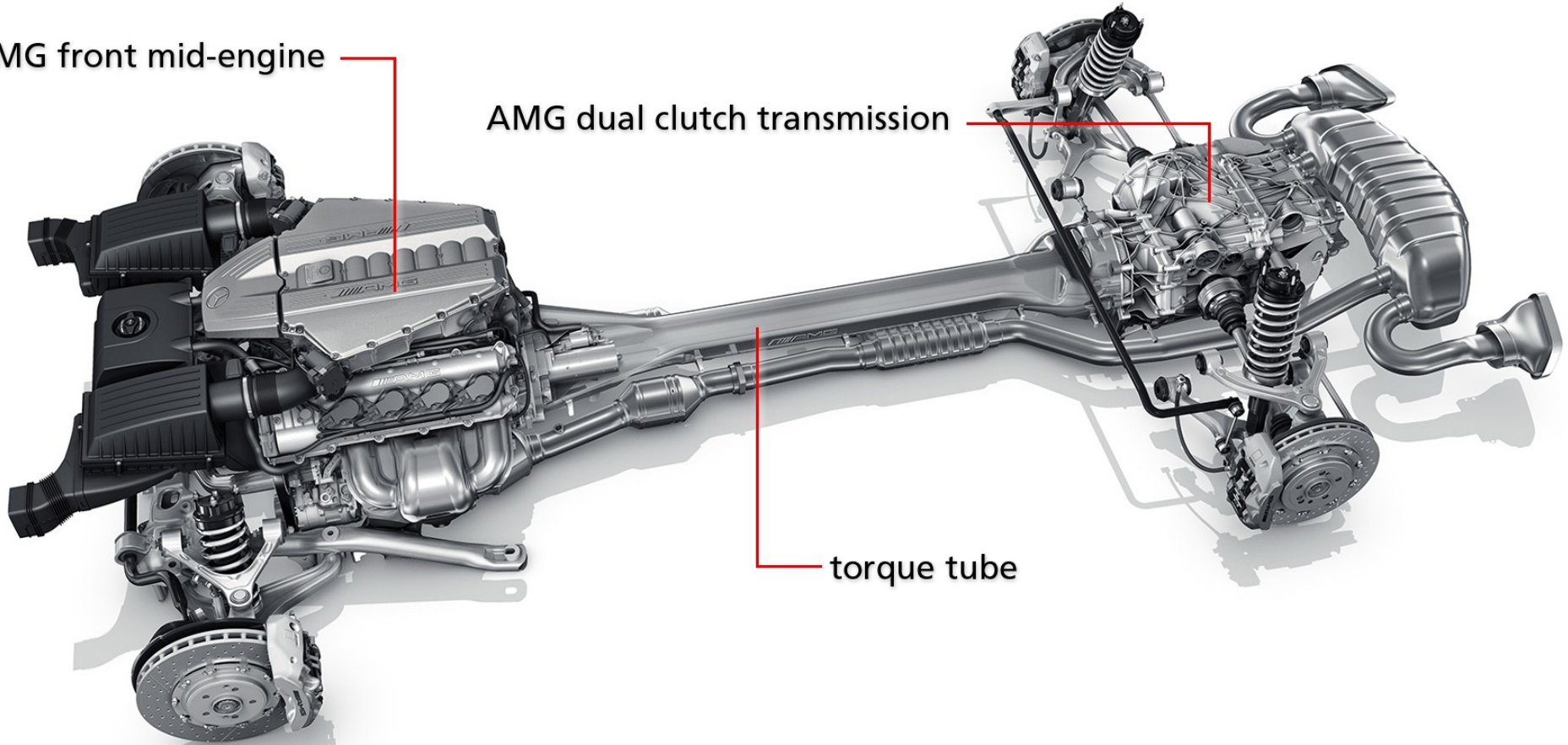


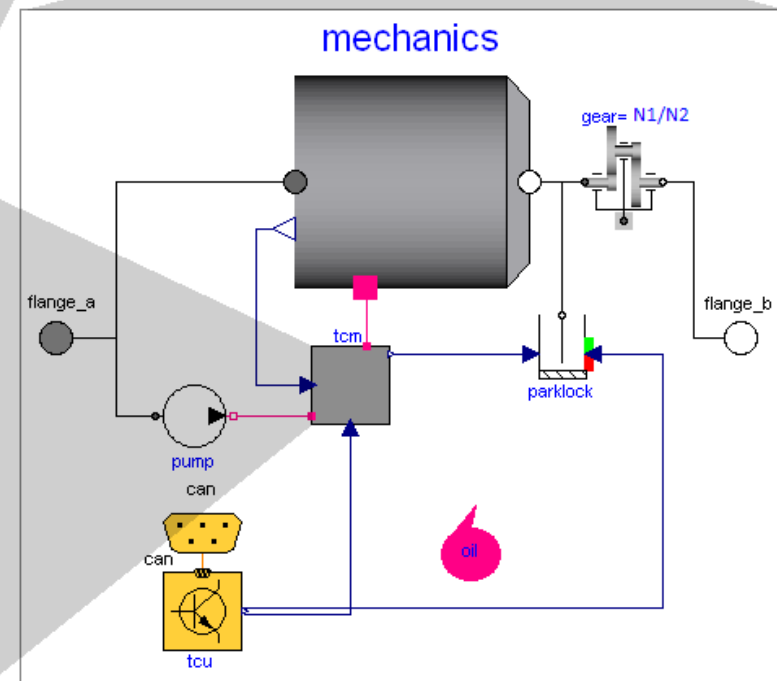
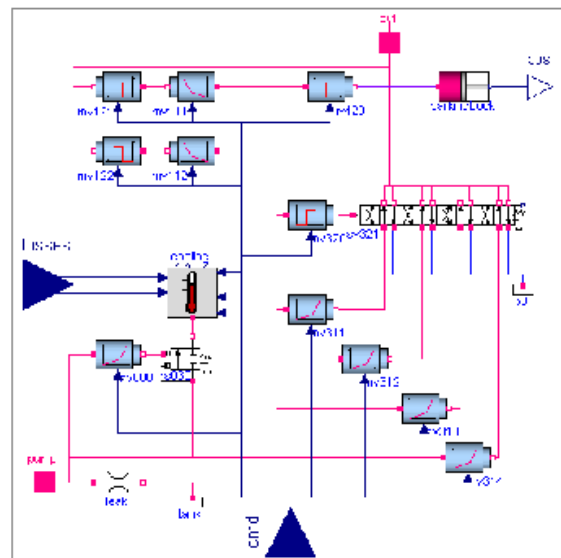
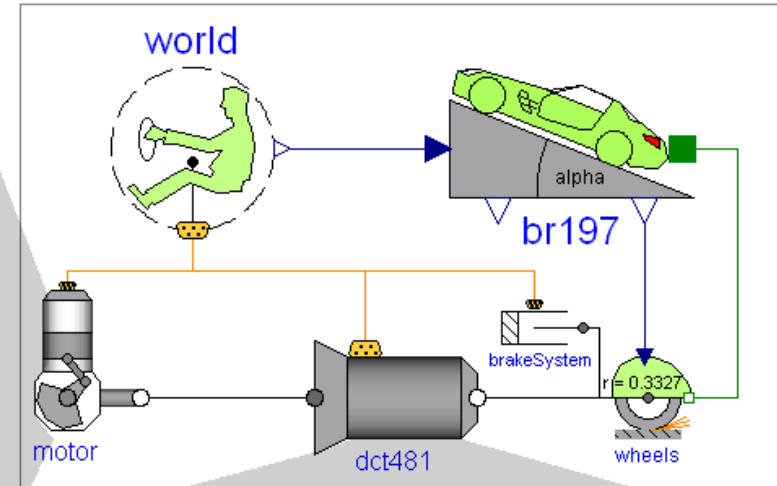
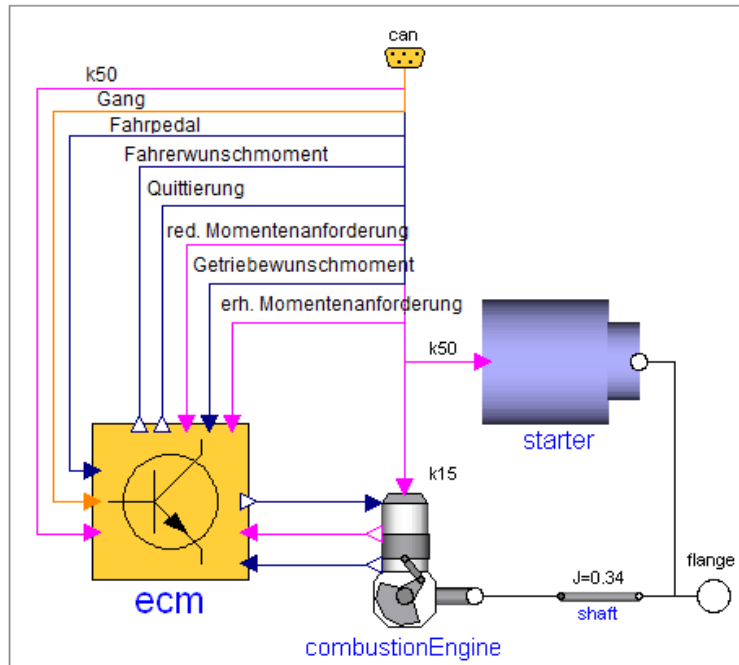
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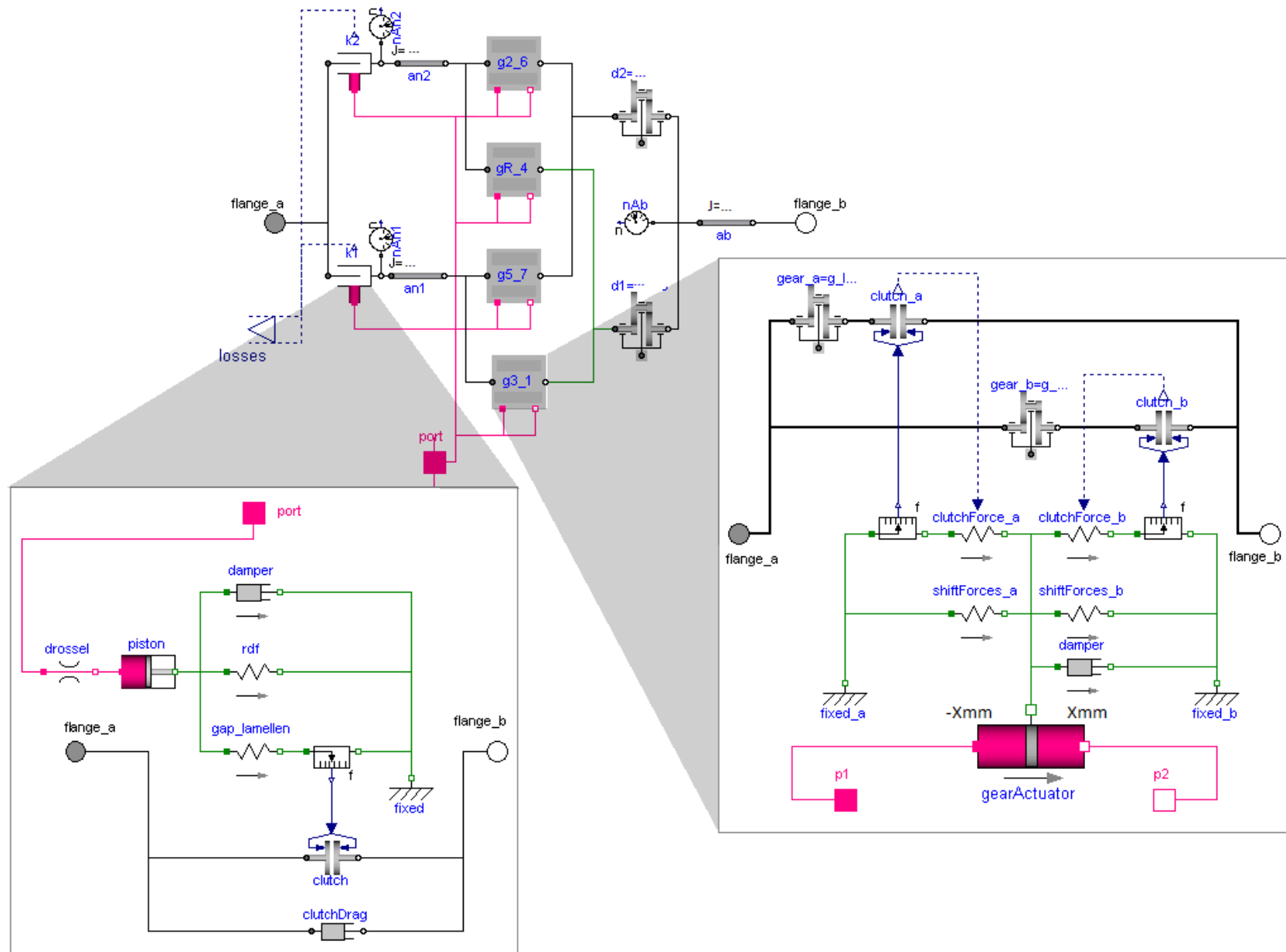
AMG front mid-engine

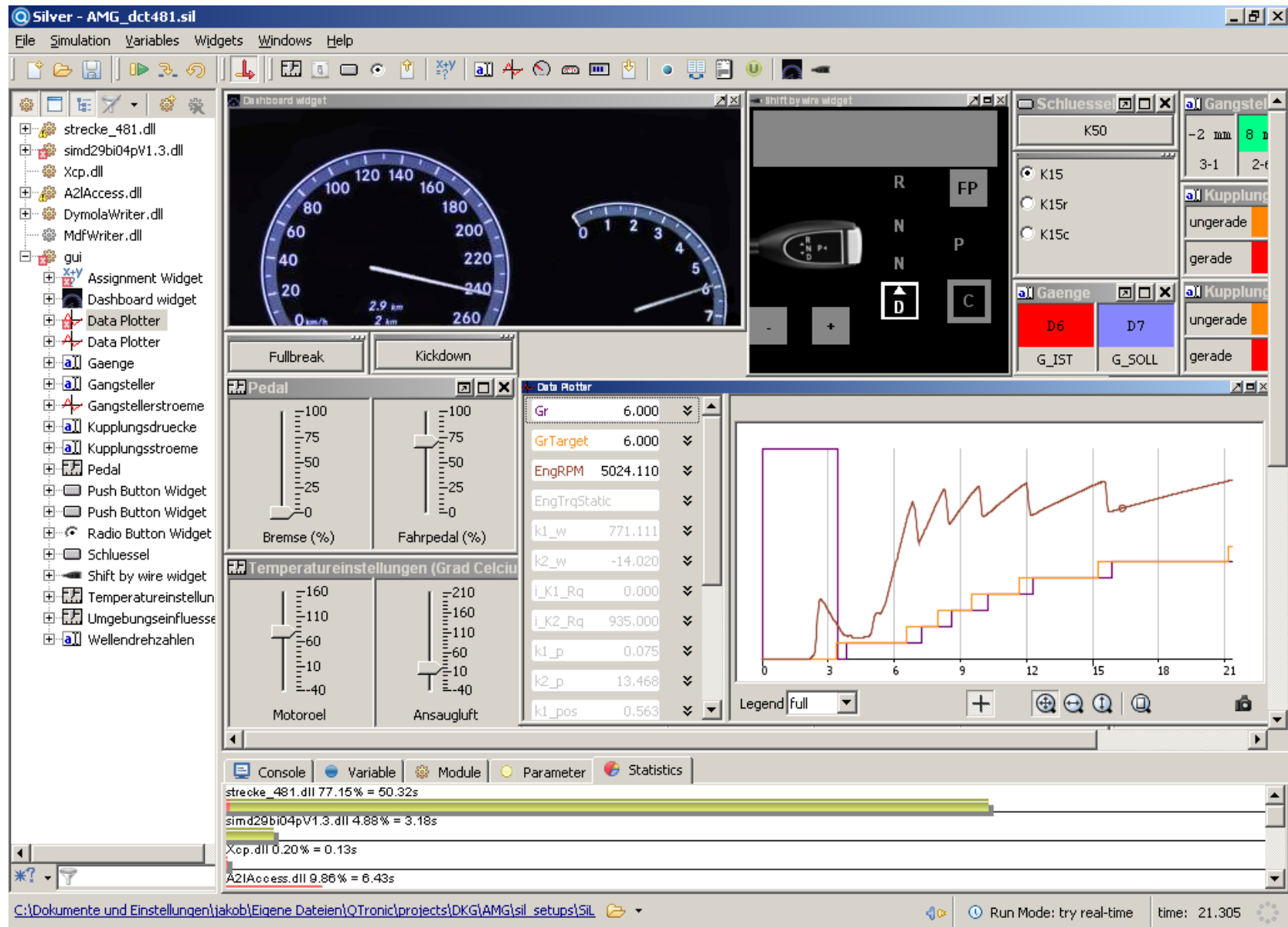
AMG dual clutch transmission

torque tube

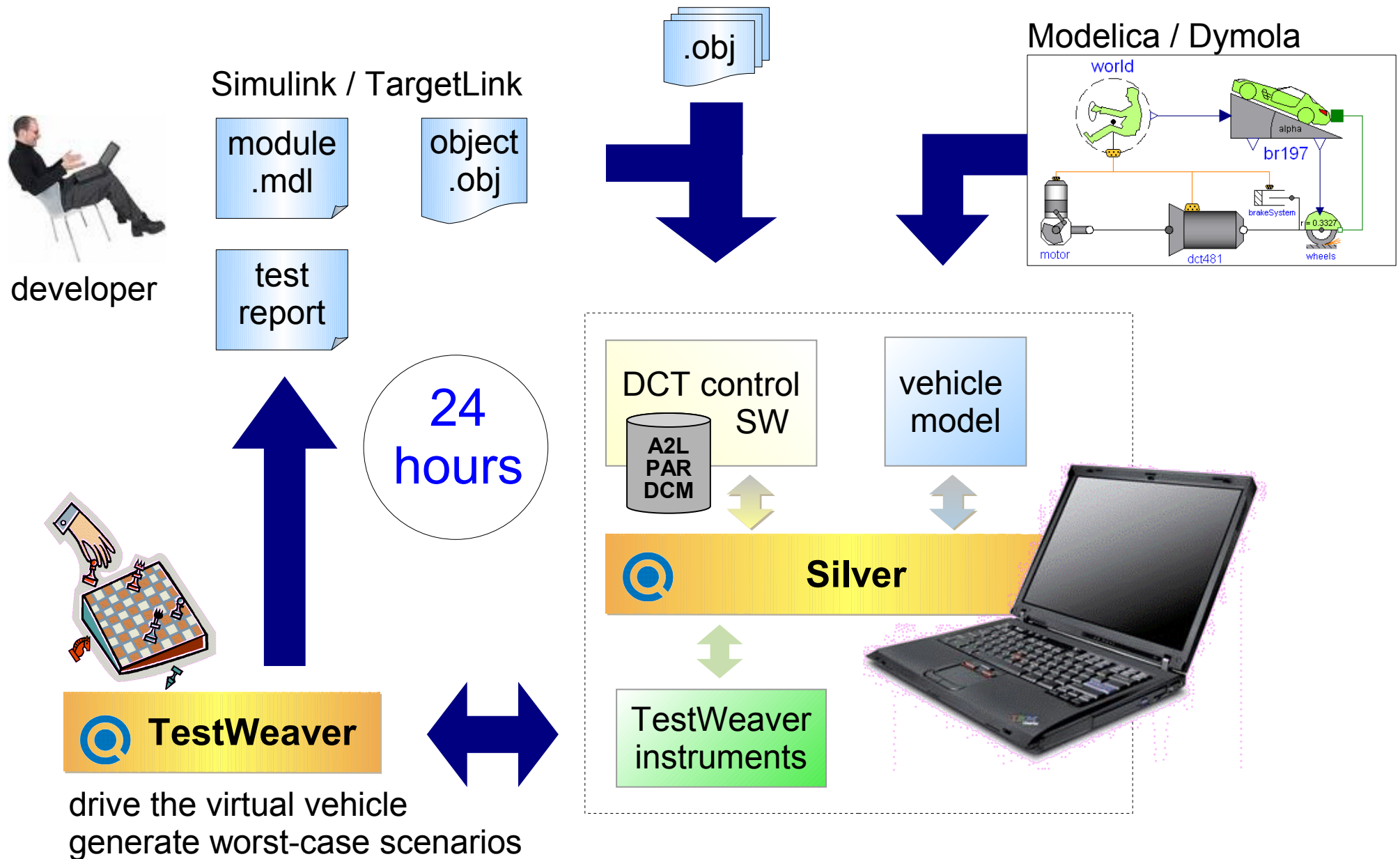








Setup of the software test



- **Runtime exceptions:**
division by zero, stack overflow...
- **A2L range monitoring:**
thousands of TCU signals...
- **Shift durations:**
average and maximal durations
- **Clutch overheating, overspeeds:**
engine overspeed or stalled...
- **DCT condition monitoring:**
> 200 signals, fault codes
- **Oscillations and unexpected control sequences:**
repeated up/down shifts, bad fault diagnosis, bad fault reaction
- **Code coverage** and system state coverage

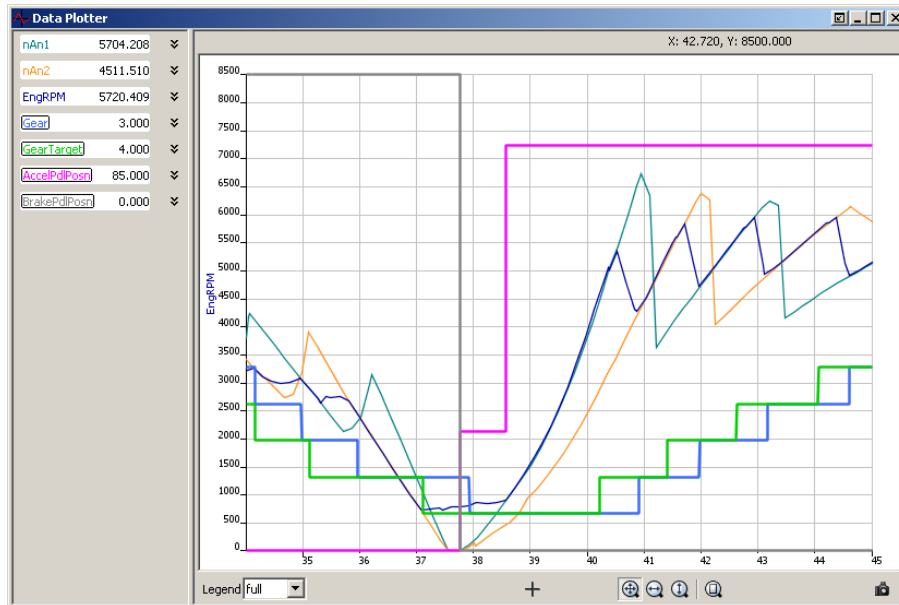


every problem reported by TestWeaver comes with one or more reproducible examples!

Example: Problem found and corrected



oscillation of target gear
- found by TestWeaver
- replay in Silver



improved control software
- run regression test
- problem solved

Test of DCT control software

- generated and analysed over 3000 different driving scenarios, each 45 sec. for every software release
- systematic test and validation with many usual and many unusual driving conditions



Conclusion

- The presented approach seems extremely well suited for the validation of automotive transmission controllers
- Necessary complement to other QA measures, test benches, prototype driving
- Main benefit:
 - much higher test coverage
 - feasible work effort

